# Short instructions for initial preparation and installation of A4xx/A6xx machines



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Jan 19, 2014

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# Short instructions for initial preparation and installation of A4xx/A6xx machines.

The goal of this manual is to offer a compact information about initial installation and startup of our machines. We will call them further "systems" having in mind that the interaction between the physical machine and software that control it creates a system during the process of use.

Some of the operations described here need to be performed either once or in rare occasions.

As an example "Home Z" (when you have changes in your stack -> backing material + PCB thickness), "Rubout tools" (only if you decide to switch to different set) etc.

The video clips links below are designed to add more practical information about the topics discussed in this manual.

HomeZ & Placing Tool in Tool Holder Demonstration (video): <u>http://youtu.be/TRNha8g7z8Q</u> Import Gerbers, Tool settings & Project aligment (video): <u>http://youtu.be/yTY14RlfLRc</u> Fiducial registration (video): <u>http://www.youtube.com/watch?v=aGGKzJjflwU</u>

# 1. Preparation of the system for usage. Software and drivers installation.

# **1.1 Cables connection**

• connect the system to grounded power outlet (Pos.1). It accepts any voltage between 100 and 250 V AC, without any voltage selectors. Do not turn it ON at this point. The power cable is normally included for most popular power outlets. In some cases we do not have access to

the type of outlets in the country of destination. In this case customers have to obtain a grounded cable that is the same as power cables used to supply the desktop computers in the particular location. The connector to the machine end is the same as on most desktop computers and is also known as IEC 60320 C13.



• connect the USB cable (included) to the machine (Pos.3) and to the computer that will be used for control. For best performance USB 2.0/3.0 port is recommended. USB 1.0 port will work too.

• connect the camera to another USB 2.0/3.0 port (extension USB cable is included).

• Connect the pressure air source (Pos.5, below). If you use our silent compressor it is factory preset to your needs. If you use other source you have to set your filter/regulator (recommended) to a value between 6-8 bar (87 to 116 PSI). Please do not exceed 8 bar/116 PSI value, this may damage the

pressure sensor embedded in the system. The procedure above is for ATC (Automatic Tool Change) models only. MTC (Manual Tool Change) models do not need pressure air.



• connect the vacuum hose to the vacuum dust collector. It is designed to accept standard 1.25 inches vacuum tubes. Usually they are conical and if you have loose connection you may cut 2-3 inches of the length to get more tight connection.



• connect the "Automatic vacuum starter" signal cable (Pos.4, 3.5 mm audio plug) for usage of commercial vacuums or the same type of plug that our vacuum/dust collecting units are equipped with. Connect the dust collecting unit to the power.

# **1.2 Software and drivers installation for PhCNC control software**

• install the control software using the CD-ROM delivered with the system or a link offered by <u>support@accuratecnc.com</u>. The installation process is completely automated, but if you have any problems you can turn to <u>PhCNC User's Manual EN.pdf</u>

- APPENDIX-H: USB drivers installation for A36x/A56x/A4xx/A6xx
- APPENDIX-I: USB drivers installation for video camera/microscope (VC)
- APPENDIX-J: PhCNC control programs installation (A350/A36x/A56x/A4xx/A6xx)

During the installation process of PhCNC the installer program installs all needed drivers.

This is the reason to recommend the software installation before the first power up of the machine. After the installation you may turn on your machine. Windows now will find and activate all needed drivers for your system and camera. Drivers for the system and camera are independent from each other and it is possible that camera drivers are already activated.

At the first communication between the machine and PhCNC software, it will check the firmware of the CNC controller, PhACdrive and PhSTdrive. Normally the CD-ROM software is up to date with the current shipment, but this feature will help you if we have firmware updates in the future. All firmware updates will be installed automatically. The process takes some time

- PhCNC360 firmware 2-3 seconds
- PhACdrive 15 to 20 seconds
- PhSTdrive less than 60 seconds

## PLEASE DO NOT INTERRUPT THE PROCESS OF FIRMWARE UPDATE!

# 2. Machine setup.

# 2.1 Machine homing.

After starting the PhCNC software, switch to CNC mode by pressing CNC button.

If you have a message that the machine is not found, it can be due to the following conditions

- machine power is off
- machine USB cable is not connected to the machine or to operating USB port on the computer.

• in rare cases USB drivers are not installed. This depend of your OS settings and antivirus barriers (programs) used. In this case you have to turn to our main manual and see the APPENDIX A - Manual USB drivers installation.

Bile CAM CNG 
 Image: Construction of the second **1** Y+ Q 35% **↑** Z+ ← X- 0.10000 X+→ ↓ z-0.001 0.01 0.1 0.5 1.0 X -1.00000 Tool: TO 4.00000 RPM: 1.22535 RPM: Feed Rat Machine in "Emergency Stop" model P A + № Θ Clear TTY no warnings X-3.03114, Y4.26075 dx-3.03114, dy-9.28924, d9.77128 2000dpi [in] Default.mpf PhCNC Pro v4.2.5.7367.A360 MTCLE: 13.5e-6/\*C (FR4) \*

Shown below is the screen shot of CNC mode.

Always after the power up and going in CNC mode, the machine is in "Emergency Stop" mode. To exit this mode you have to push/reliase the "Emergency Stop button" (see above). In the next step you will receive a prompt to Home the machine. If it is real first emtry in CNC mode after power up the mandatory answer is "Yes". If you use the "Emergency Stop" during the operation without power interuption you may select "No". Our systems do not loose coordinates during the "Emergency Stop" action.



After the homing the system is ready for use.

## Important:

If the air pressure indicator is blincking 🤶 you need to check the pressure air connection and presure level.

# 2.1 Placing the tools in the tool holders.

In order to have fully automatic mode all tools needed for the project must be placed in to the machine tool holders. Conditionally speaking we divide the tools in two groups, permanent and specific. The permanent tools are the ones that are always needed. Typical arrangement includes.

- one tool for insulation process
- one tool for cutting (routing).
- 2, 3 or 4 tools for copper rubout

• the rest of tool holders (6 or 10 depend of the machine model) are for small diameter drill bits. These are specific for the project.

• drilling of holes that are larger than cutting tool can be assigned to the cutting tool and routed with it. This SW function reduces the number of tools needed and makes the drill diameter unlimited.

All ATC models allow manual tool change in case that it is needed.

The tools in the holders have to have description entered. They will be used in ATC mode only when the description matches the one in your "project tools" table. PhCNC will list them as placed in the tool holder number **THOS** or for manual tool change **S**. If any particular tool is in the tool holder, but is still listed for manual tool change the description entered is different from the one in your "Project tools" table and need to be corrected.

Seems that the most practical way is to enter all descriptions in the "Tool Table" and select the existing description for the tool in the respective holder.

Using the ATC Control Panel **Control** is the best way to handle all information related to the tools in use.



In the initial power up "ATC Control Panel" will ask you to check the status of the tool holders and spindle collet. Normally the machine comes with a blank tool in the collet (transportation tool) and empty tool holders. It is very recommended to answer "Yes" and see the result. It should show empty tool holders and "unknown" tool in the spindle collet.

#### **Important:**

The test above sets the information for tool logistics. It is very important. In addition the system checks the status of the particular tool holder before and after tool change operation to assure that the process is completed correctly. THIS FUNCTION CAN BE PERFORMED ONLY AFTER MACHINE HOMING!

Placing and removing the tools in/out the tool holders.

Both placing and removing the tools in and out of tool holders by hand is physically possible, but we definitely **DO NOT RECOMMEND IT**. Here are the reasons:

• placing the tool in the tool holder by hand may leave the tool not strait up. As a result when the spindle is trying to pick the tool it may push it down and damage the infrared sensor located in each tool holder.

• hand removal do not impose any dangers, but in both cases you have to run "Tool Holders Check" in order to inform the system for the new tools logistic. As a bottom line this will not give you any advantages. Please use the process described below for tools placement and removal.

#### Start-up step-by-step



Select the tool holder that you like to place the tool (TH01 is shown on the screen shot above). Press Place Tool , If the spindle already has a tool in the collet it will place it in the TH01, if it is empty will come to the tool change position and will prompt you to place tool in the collet. After placing the tool in the collet it will check the actual tool existence and then will place it in the selected tool holder. As a first step we recommend you to request "Manual tool change" and remove the blank tool used for machine transportation.

No. Contraction of the second	And the second s		
Eile CAM CNC Setup Tools Calc	X ATC Control Panel	× 1	
🕇 Y+ 🔍 Q 359	96 🕑 @ ATC tool holders: 16 empty 4 4 3 3 - 3 5 CNC Control Panel	Tool Holders Check	Change 🛞 👼
← X- 0.10000 X+→	Syindle 🗖	Return Tool	Program:
↓ γ- ↓ Z-	THOI _		RUN (GD) Stop
1 µm 0.001 0.01 0.1 0.5 1.0	THO2 C	Get Tool	MDI:
X -1.00000 Tool: TO		Place Tool	
Y 4.00000 RPM: 0		Replace Tool	
Z 1.22543 RPM: 0		Tool settings	
Home XY			😂 Open 🛛 🚓 Compile
Home Y		Manual tool change	
Home Z X=0 Y=0 Z=0		Open splindle's collet	
Spindle	THUB II	Park	
Spindle ON SUP			
	PhCNC -> Change Tool!	STOP	
0 rpm 0 60000 rpm	Please change the tool	Emergency Stop	
Feed Rate Ovende		Check tool's ring	
+15% 0.0% -25%	Please, use the button "target" to open/close the splindle's collet!	rgency Auto tool depth aton	
	Confirm to continue!	Manual depth control	
Park V + M			
Clear TTY			
LS Z+: 1.23134"	Project tools: 0 in ATC tool holders, 2 in undefined location Depth	milj: ×	
LS X: -1.03496" LS Y: -1.30000"	(3.7) mil		
	(80.0) m R_39	il 🛛	
		0 0 0 0	
			Power: 0.00W I: 0.00A
			Ls: -3.0µm Board: 28.9°C Status: PWM:Off
			[Nm] [A]
			Ex 💽 🖓 😽
vinos j	ings X5.63231, Y11.53268 dx5.63231, dy-2.01733, d5.98269 2000dpi [in] Default.mpf PhCNC Pro v4.2.5.73	17.A360 MTCLE: 13.5e-6/*C (FR4) @	24.14°C

Placing a tool in the spindle collet is a process that is very easy and is well assisted with the "Manual tool changer". It comes included in all of our systems.



#### Manual tool changer

Once in a manual tool change position you will be able to control the spindle collet. Pushing the button on the calibration pad will open the spindle collet. During the inserting the tool, apply small up force in order to have the plastic ring touching the collet lips during the closing. Release the button to close the spindle collet (Pos.7).



In order to place the tool in the tool holder you have to click on the "OK" button. SW will check for the real tool existence in the collet and its proper position (using the calibration station) and will place it in the selected tool holder. Screen shot is shown below.



Next step is to enter/edit the tool description. Double click on the description field will call the tool table

#### Start-up step-by-step

Diameter A Type Operation Speed Plungerate Feed rate Tool Tip Comment											
ŧ1	[in] 0.010	Stub End Mill	All	[rpm] 50000	[in/m] 35.0	[in/m] 7.5	[mil] -	comment			
+2	0.016	Stub Fod Mill	All	default	default	default	-	SEM 15			
3	0.0197 (0.5mm)	Stub End Mill	All	default	default	default	-				
4	0.025	Stub End Mill	All	default	default	default	-				
5	0.0313 (1/32")	Stub End Mill	Insulate & Rubout	default	default	default	-				
6	0.0625 (1/16")	Stub End Mill	All	default	default	default	-	SEM 63			
7	0.125 (1/8")	Stub End Mill	All	default	default	default	-	SEM 125			
8	0.0135	Drill bit	Drill	default	default	-	-	 DRL_13.5			
9	0.022	Drill bit	Drill	default	default	-	-	 DRL_21.65			
10	0.026	Drill bit	Drill	default	default	-	-	-			
11	0.0313 (1/32")	Drill bit	Drill	default	default	-	-	DRL_31			
12	0.035	Drill bit	Drill	default	default	-	-	DRL_39			
13	0.047	Drill bit	Drill	default	default	-	-	DRL_47			
14	0.079	Drill bit	Drill	default	default	-	-	DRL_79			
15	0.1181 (3.0mm)	Drill bit	Drill	default	default	-	-	DRL_118			
16	0.125 (1/8")	Drill bit	Drill	default	default	-	-	DRL_125 #1			
17	0.125 (1/8")	Drill bit	Drill	default	default	-	-	DRL_125 #2			
18	0.125 (1/8")	Drill bit	Drill	default	default	-	-	DRL_125 #3			
19	undef	"V" 30°	Insulate & Rubout	default	default	default	3.5	¥_30			
20	undef	"V" 45°	Insulate & Rubout	45000	default	default	6.5	¥_45			
21	undef	"¥" 60°	Insulate & Rubout	default	default	default	5.8	¥_60			
22	undef	"V" 90°	Insulate & Rubout	default	default	default	4.0	V_90			
23	0.0313 (1/32")	Router bit	Cut & Drill	default	default	default	-	R_31			
24	0.0394 (1.0mm)	Router bit	Cut & Drill	default	default	default	-	R_39			
25	0.049	Router bit	All	default	default	default	-	R_49			
26	0.050	Router bit	Cut & Drill	default	default	default	-	R_50			
27	0.0984 (2.5mm)	Router bit	Cut & Drill	default	default	default	-				
28	0.1181 (3.0mm)	Router bit	Cut & Drill	default	default	default	-				
	+ Add							1 cala			

If the tool is not existing in the tool table it can be added using \_\_\_\_\_ button

	Diameter [in]	🔺 Type	Operation	Speed [rpm]	Plunge rate [in/m]	Feed rate [in/m]	Tool Tip [mil]	Comment
#1	0.010	Stub End Mill	All	50000	35.0	7.5	-	
12	0.016	Stub End Mill	All	default	default	default	-	SEM_15
3	0.0197 (0.5mm)	Stub End Mill	All	default	default	default	-	
14	0.025	Stub End Mill	All	default	default	default	-	
5	0.0313 (1/32")	Stub End Mill	Insulate & Rubout	default	default	default	-	
f6	0.0625 (1/16")	Stub End Mill	All	default	default	default	-	SEM_63
ŧ7	0.125 (1/8")	Stub End Mill	All	default	default	default	-	SEM_125
8	0.0135	Drill bit	Drill	default	default	-	-	DRL_13.5
9	0.022	Drill bit	Drill	default	default	-	-	DRL_21.65
#10	0.026	Drill bit	Drill	default	default	-	-	
#11	0.0313 (1/32")	Drill bit	Drill	default	default	-	-	DRL_31
#12	0.035	Drill bit	Drill	default	default	-	-	DRL_39
13	0.047	Drill bit	Drill	default	default	-	-	DRL_47
<b>#1</b> 4	0.079	Drill bit	Drill	default	default	-	-	DRL_79
15	0.1181 (3.0mm)	Drill bit	Drill	default	default	-	-	DRL_118
16	0.125 (1/8")	Drill bit	Drill	default	default	-	-	DRL_125 #1
#17	0.125 (1/8")	Drill bit	Drill	default	default	-	-	DRL_125 #2
18	0.125 (1/8")	Drill bit	Drill	default	default	-	-	DRL_125 #3
#19	undef	"¥" 30°	Insulate & Rubout	default	default	default	3.5	¥_30
\$20	undef	"¥" 45°	Insulate & Rubout	45000	default	default	6.5	¥_45
21	undef	"¥" 60°	Insulate & Rubout	default	default	default	5.8	¥_60
\$22	undef	"V" 90°	Insulate & Rubout	default	default	default	4.0	¥_90
#23	0.0313 (1/32")	Router bit	Cut & Drill	default	default	default	-	R_31
#24	0.0394 (1.0mm)	Router bit	Cut & Drill	default	default	default	-	R_39
#25	0.049	Router bit	All	default	default	default	-	R_49
#26	0.050	Router bit	Cut & Drill	default	default	default	-	R_50
127	0.0984 (2.5mm)	Router bit	Cut & Drill	default	default	default	-	
28	0.1181 (3.0mm)	Router bit	Cut & Drill	default	default	default	-	
H01	undef 🛛 😪	undefined 🗸	undefined 🛛 🗹	default 💌	default 💌	default 💌	-	

Below is an example of new tool description.

• Diameter: undef (V tools are typical insulation tools and allow different insulation gaps related to the tool penetration).

- Type: V90 (90 deg conical cutter)
- Operation: Insulation & Rubout (the tool will be used in selected operations)

• Speed [rpm]: default (will set default speed for the operation selected)

• Plunge rate [in/m]: default - the speed that the tool will penetrate in the material. Will use the penetration rate for selected operation.

• Feed rate [in/m]: default - the movement speed in XY plane during the machining. Will use the speed rate for selected operation.

#### Note:

All default values can be changed to particular values using the drop down menus.

• Tool Tip [mil]: important parameter that apply for V tools only. If not published by the vendor or manufacturer it can be measured using a measuring microscope or found by "tool test" function embedded in PhCNC software. Typical tip diameter for the V tools is 4-5 mil.

Too	ol Table							
	Diameter [in]	🔺 Туре	Operation	Speed [rpm]	Plunge rate [in/m]	Feed rate [in/m]	Tool Tip [mil]	Comment
#1	0.010	Stub End Mill	All	50000	35.0	7.5	-	
#2	0.016	Stub End Mill	All	default	default	default	-	SEM_15
#3	0.0197 (0.5mm)	Stub End Mill	All	default	default	default	-	
#4	0.025	Stub End Mill	All	default	default	default	-	
#5	0.0313 (1/32")	Stub End Mill	Insulate & Rubout	default	default	default	-	
#6	0.0625 (1/16")	Stub End Mill	All	default	default	default	-	SEM_63
#7	0.125 (1/8")	Stub End Mill	All	default	default	default	-	SEM_125
#8	0.0135	Drill bit	Drill	default	default	-	-	DRL_13.5
#9	0.022	Drill bit	Drill	default	default	-	-	DRL_21.65
#10	0.026	Drill bit	Drill	default	default	-	-	
#11	0.0313 (1/32")	Drill bit	Drill	default	default	-	-	DRL_31
#12	0.035	Drill bit	Drill	default	default	-	-	DRL_39
#13	0.047	Drill bit	Drill	default	default	-	-	DRL_47
#14	0.079	Drill bit	Drill	default	default	-	-	DRL_79
#15	0.1181 (3.0mm)	Drill bit	Drill	default	default	-	-	DRL_118
#16	0.125 (1/8")	Drill bit	Drill	default	default	-	-	DRL_125 #1
#17	0.125 (1/8")	Drill bit	Drill	default	default	-	-	DRL_125 #2
#18	0.125 (1/8")	Drill bit	Drill	default	default	-	-	DRL_125 #3
#19	undef	"V" 30°	Insulate & Rubout	default	default	default	3.5	¥_30
#20	undef	"V" 45°	Insulate & Rubout	45000	default	default	6.5	¥_45
#21	undef	" <b>V"</b> 60°	Insulate & Rubout	default	default	default	5.8	¥_60
#22	undef	"V" 90°	Insulate & Rubout	default	default	default	4.0	¥_90
#23	0.0313 (1/32")	Router bit	Cut & Drill	default	default	default	-	R_31
#24	0.0394 (1.0mm)	Router bit	Cut & Drill	default	default	default	÷	R_39
#25	0.049	Router bit	All	default	default	default	-	R_49
#26	0.050	Router bit	Cut & Drill	default	default	default	-	R_50
#27	0.0984 (2.5mm)	Router bit	Cut & Drill	default	default	default	-	
#28	0.1181 (3.0mm)	Router bit	Cut & Drill	default	default	default	-	
#29	undef 🗹	"¥" 90° 🛛 🗹	Insulate & Ruboi 🍸	default 🕑	default 💌	default 💌	4.5 💌	
	+ Add -	Delete						Select

After final entry of the parameters (of a new tool) or selection of existing one you have to click on "Select" button and this will transfer the description to the currently selected tool holder. Shown on the screen shot below.

#### Start-up step-by-step



This procedure have to be performed for each tool that is in the tool holders in order to be used in ATC mode. It may looks to complicated, but once your tool table contains all tools that are in use it takes just a few seconds to select the description for the particular tool holder. Shown bellow is ATC control panel with tools descriptions entered.



# 3. PCB material (work piece) fixing on the table

We offer 4 different ways of fixing (mounting) of the PCB and backing material on the machine table. The usage is related to the configuration (camera/microscope, vacuum holding table). The systems equipped with vacuum table may use all mounting options.

First of all we like to remind the operator that exact position of mounting the material (to be machined) is not important. The positioning match of the material and project can be synchronized later, moving/placing the project on the desired position over the material.

Below are the 4 ways of mounting

**1.** Taping all for sides of the backing material to the table, then taping all four sides of the material on the backing (can be used with camera option only).

• Advantages: easy, fast and inexpensive way

• Disadvantages: inserts positioning error that may exceed 1 mil (25 microns) in any directions due to the tape flex. Lost of usable surface due to the fact that the pressure foot (1" dia, 25 mm) don't have to go over the tape. Usable surface is inside the red rectangle shown below.



**2.** Using double sided (double sticky) tape to mount the backing material on the table and to mount the material (to be machined) on the backing material (can be used with camera option only).

• Advantages: No any kind of losses in accuracy. Behaves the same way as "Vacuum holding table". No lost surface of the material under machining (important when expensive RF materials are used). No need of relatively expensive vacuum table and generator. Significant savings in energy consumption. The most recommended for use.

• Disadvantages: Slightly more expensive tape is used.



Shown above is application of 1/2 inch (~ 13 mm) tape. It should be placed on the bottom side of backing material and your work piece. Shown below is assembled stack. Entire surface of the PCB material can be used.



3. Using vacuum holding table (can be used with camera option only).

• Advantages: No losses in accuracy. The best way to handle very thin substrates down to 5 mil (0.12 mm).

• Disadvantages: More expensive configuration. Vacuum table and vacuum generator option need to be included in configuration. More energy usage during the operations due to constantly running vacuum generator.

Shown below is the predrilled backing material. Sample of it comes with the system. Also included in the PhCNC is automatic generation of G code for any size of backing material to be

predrilled at needed pattern. Recommended hole size is 0.08 inches (2 mm). To create your backing material place two layers of it on the table and generate the needed G code for drilling.



Shown above is the pre dilled backing material. 2 small pins 1/16 (1.5 mm) needed to align the holes are included.



Shown above is mounted PCB material. You have to cover unused part of the table with standard printer paper. Minimum size of work piece is 10 square inches (64 square cm).

As shown below the optimum vacuum is 80 inches (2 meters) of water column. If it tends to go below 60 inches (1.5 meters) due to large openings in the project, the operator need to increase the speed of vacuum generator in order to get the needed vacuum. Vacuum column below 60 inches may cause moving of the work piece and unpredictable errors in the machined surfaces.



**4.** Using registration pins. This option is offered in all system (except these with vacuum holding table) as a second option for material installation.

• Advantages: strong "in position" holding. Recommended for (non ferrous) metals machining. No need of camera option. Saves about a minute needed for fiducial (optical) registration after board flip over.

• Disadvantages: less accurate compare to fiducial (optical) registration. Requires predrilled backing material and material under machining for the holes needed for the registration pins.

Once the material is mounted on the table it is needed to perform **Home Z** command. Place the milling head over your material and click on "**Home Z**" button. The reading from this procedure remains valid until the next "**Home Z**" procedure. In other words you need to repeat it only when you have change in the height of your stack (backing material + work piece).

In the video clip below you can see the procedures mentioned above.

HomeZ & Placing Tool in Tool Holder Demonstration: http://youtu.be/TRNha8g7z8Q

# 4. Gerber and drill files import. Tools selection.

# 4.1 Gerber files import

In order to create a board using our system you have to import the files generated from a PCB CAD system. Typically they are a set of a few files, containing all information that is needed for the complete description of the board. This set of files is the same that you have to send to the board shop in order to manufacture board(s) for you. Normally the set consist of Gerber files for TOP COPPER, BOTTOM COPPER, MECHANICAL for inside and outside cutouts and drill file in Excellon format. In order to start this

process you have to click on this button (CAM mode) **\*\***. Sown below is a screen shot of this process. After you finish, click on "Import" button (upper right corner of the screen)

👬 Gerber & Drill Import		
Select C:\Program Files (x86)\PhCNC Demo\SAMPLES\T	ERMOSENSE 🛛 🗸 🍫	Layers:
Vame	Date/Time Size	Top Bottom Mech Stop Stop TERMOSENSE: 1.899" x 1.213"
🗀 -		Top Bottom Mech Stop
TERMOSENSE.BOT	14-12-2008 19:09:18 4 K	K Top Bottom Mech Strop Concil
TERMOSENSE.MEC	14-12-2008 19:09:18 0 K	🗹 Top 🔲 Bottom 🦉 TERMUSENSE.
TERMOSENSE.Lap	14-12-2008 19:09:16 0 K	
TERMOSENSE.TOP	14-12-2008 19:09:18 8 K	K Strategy (Strategy (Stra
		Photoplot resolution [dpi]: 2,000 💮 Mirror X Mirror Y TERMOSENSE.tan
		Q 187% V Q B
		Profie: Default.mpf 2.505" x 1.765"
c:\\Program Files {x86}\PhCNC Demo\SAMPLES\TERMOSENSE\TERM	OSENSE.t. 14-12-2008 17:09:18	8 1 KB X-4.5954, Y-2.9537" dX-4.5954, dY-2.9537, d5.4628" dX-116.7243, dY-75.0228. d138.7551 mm

Shown below is the screen shot of the imported project in PhCNC:



# 4.2 Selecting the copper rubout region(s)

When complete copper removal is needed you have to select the region(s) to be treated. Common case is that the entire board surface is selected. You can have many different selections including different regions on top and bottom of the board. Number of selected regions is unlimited. For more details of this process turn to main manual. To start the selection click on this button  $\blacksquare$ . Using your mouse select the region(s).



This button will show/hide the copper rubout region(s). The first click on it will initiate the tools paths calculations.

# 4.3 Tools selection

All tools in the project are listed in the Project Tools window. To see it click on UProject.

Vroject Tools										
Project tools: 6 in AT	C tool holders, 5 in undefined location	Depth [mil]:	Rubout Tools							
🗇 🖁 Insulate TO	"V" 90° Tip{0.0000"/0.000mm} {Insulate,Rubout} V_90	(4.7) mil	~ serdh							
TH 13 Cut TO	Router bit 0.0394"/1.001mm {Drill,Cut} R_39	(80.0) mil								
TH03 Rubout T1	Stub End Mill 0.0100"/0.254mm (Insulate,Rubout,Drill,Cut,Stencil) FR7.5	(3.0) mil								
THD4 Rubout T2	Stub End Mill 0.0156"/0.397mm {Insulate,Rubout,Drill,Cut,Stencil} FR7.5 SEM_15	(3.0) mil								
THUS Rubout T3	Stub End Mill 0.0313"/0.795mm {Insulate,Rubout}	5.0 mil								
THUE Rubout T4	Stub End Mill 0.0625"/1.587mm {Insulate,Rubout,Drill,Cut,Stencil} SEM 63	(3.0) mil								
TH07 Rubout T5	Stub End Mill 0.1250"/3.175mm {Insulate,Rubout,Drill,Cut,Stencil} SEM_125	(3.0) mil								
🕞 🖁 Drill T1	Drill bit 0.0310"/0.787mm T1C0.031F2005100	(80.0) mil								
🕞 🖁 Drill T2	Drill bit 0.0390"/0.991mm T2C0.039F2005100	(80.0) mil								
🕞 🖁 Drill T3	Drill bit 0.0590"/1.499mm T3C0.059F2005100	(80.0) mil								
🕞 🖁 Drill T4	Drill bit 0.1100"/2.794mm T4C0.110F2005100	(80.0) mil								
			Auto tool depth update							

All tools that have a description matching the description of the tool located in a tool holder will be assigned to ATC process (ATC models only). For example <sup>100</sup>.

Tools that have this symbol *w* do not have the description that match the tool needed in your project and will require manual tool change during the machining process. If you think that the tool needed is already in a tool holder, simply review the description and find what is the difference that prevent the proper selection and correct it. In a classic case you will have differences only in small drill bits diameters. The best solution is to replace them in the tool holders and run fully automatic mode.

# 4.3.1 Insulation tool

You can select your insulation tool according to requirements of your project. Using the button V set the needed insulation tool and select it from existing in tool holders. In the example below it is located in TH01.

Project Tools			
Project tools: 6 in ATC	tool holders, 5 in undefined location	Depth [mil]:	V Insulate Tool Setup
TH01 Insulate TO	"Y" 90° Tip{0.0045"/0.114mm} {Insulate,Rubout}	2.5 mil 🛛 💌	
TH 13 Cut TO	Router bit 0.0394"/1.001mm {Drill,Cut} R_39	(80.0) mil	
TH03 Rubout T1	Stub End Mill 0.0100"/0.254mm {Insulate,Rubout,Drill,Cut,Stencil} FR7.5	(3.0) mil	
TH04 Rubout T2	Stub End Mill 0.0156"/0.397mm {Insulate,Rubout,Drill,Cut,Stencil} FR7.5 SEM_15	(3.0) mil	
TH05 Rubout T3	Stub End Mill 0.0313"/0.795mm {Insulate,Rubout}	5.0 mil	
THOS Rubout T4	Stub End Mill 0.0625"/1.587mm {Insulate,Rubout,Drill,Cut,Stencil} SEM_63	(3.0) mil	
TH07 Rubout T5	Stub End Mill 0.1250"/3.175mm {Insulate,Rubout,Drill,Cut,Stencil} SEM_125	(3.0) mil	
🕝 🖁 Drill T1	Drill bit 0.0310"/0.787mm T1C0.031F2005100	(80.0) mil	
🕞 🖁 Drill T2	Drill bit 0.0390"/0.991mm T2C0.039F2005100	(80.0) mil	
🕝 🖁 Drill T3	Drill bit 0.0590"/1.499mm T3C0.059F2005100	(80.0) mil	
( 기 및 Drill T4	Drill bit 0.1100"/2.794mm T4C0.110F2005100	(80.0) mil	
			Auto tool depth update

# 4.3.2 Cutting tool

Similar to the insulation tool is the selection of the cutting tool. In most cases (when the project are coming from the same designer) these tools are permanent as a size and penetration settings.

Real PhCNC						
Eile CAM CNC Setup Tools Calc						
🚅 🎇 🚔 🤯 🚔 🔍 🖉 🖻	रे 🗄 📆 🛃 📡 🖾 🐗	B B→B S CNC SPro	ject Is (4!)			Options, 💽 📥 🗠 🏭
						La construction de la constructi
	Project Tools				X	
🗑 Insulate 8.00 mil 💉 TO	Project tools: 6 in ATC t	tool holders, 5 in undefined location		Depth [mi]: UCut 1		
UL 39.37 mil V T1	TH01 Insulate T0	"¥" 90° Tip{0.0045"/0.114mm} {Ins	ulate,Rubout}	2.5 mil	P	
vubout tools: 0.125, 0.063, 0.031, 0.016, 0.010, 0.008	TH13 CULTO	Router bit 0.0394"/1.001mm {Drill,Ci	#}	(80.0) mil 🔽		
u drill tools: 0.031, 0.039, 0.059,	TUDE Rubout T1	Stub End Mill 0 0100"/0.25.4mm Class	date Rubeut Drill Cut Etencil)			
◎ 0.110		FR7.5 Cutting tool				
	Rubout 12	FR7.5 SEM Diameter (d) [in]: I	0.0394 🕑 <u>O</u> K			
(型)	THUS Rubout T3	Type:	Router bit	t Tool		
	TH06 Rubout T4	SEM_63 Feed rate[in/m]: (	(7.5) V Selec	t Tool		
	TH07 Rubout T5	Stub End N Plunge rate[in/m]: ( SEM_125	(20.0)			
Top Layer	🗇 🖁 Drill T1	Drill bit 0.0 Speed [RPM]: 1		mil		
TERMOSENSE.tap	🗇 🖁 Drill T2	Drill bit 8.0 T2C0 0295 Papetration Depth [mil]:	80.0	mil		
Bottom Layer	CP V Drill T3	Drill bit 0.6				~
TERMOSENSE.MEC		ol Table				
	<u> </u>	Diameter 🔺 Type [in]	Operation Speed [rpm]	[in/m] [in/m]	Tool Tip Comment [mil]	
	THOS	0.010 Stub End Mill	All 50000	35.0 7.5	-	
		0.016 Stub End Mill	All default	default default	- SEM_15	
		0.0625 (1/16") Stub End Mill	All default	default default	- SEM_63	
		0.125 (1/8") Stub End Mill	All default	default default	- SEM_125	
		) 0.0394 (1.0mm) Router bit	Cut & Drill default	default default	- R_39	
		0.055 Router bit	Cut & Drill derault	deraulc deraulc	- R_50	
[Obj[1]: "TERMOSENSE.TOP"]						
size [in]: 2.464 x 1.718						
tool ptots: 64.19 in durations - 5.02 min (E15.0 in/m)						
[Obi[2]: "TERMOSENSE BOT"]					y Calar	et .
total area [in2]: 4.233					a see	
4 4 warnings X	K7.93209, Y6.07524 dx7.93209, dv-7	.47476. d10.89909 2000dpi [in]	Default.mpf PhCNC	Pro v4.2.5.7367.A360 MTC	LE: 13.5e-6/*C (FR4) @ 24.14*C	

Selected cutting tool is located in TH13.

# 4.3.3 Rubout tools

If the project contains copper rubout region(s) the "Project tools" table will have them listed.

They have to be changed in rare cases. The philosophy of the sizes can be described this way.

First rubout tool is always the insulation tool. All other sizes are twice the diameter of the previous. This create a maximum efficiency in the process. In some cases (small size of surface to be treated) the larger tools can be eliminated. We are typically using (in addition to the insulation tool) the following sizes 15 mil, 32 mil, 62 mil, 125 mil. Any metric values similar to this will do the job fine. The only requirement is to enter the real diameters of the tools. This will allow the software to create the right tool pats for the process.



Rubout tools can be selected in the "Project Tools" table too.

PhCNC						-			<u> </u>			
File CAM CNC Setup Tools Calc				viect								
<b>*</b> ₩ <b>*</b> <u>₩</u> <b>* * * *</b>	12% 🕐 🍳 🖾 71 💆 🕅 🖻	4 ≝ ≝→≝	CNC To	ols (4!)							Options,	
🖙 💦 🛋 🔜 🔜									¥			
👹 Insulate 8.00 mil 💌 TO	Project Too	bis	6 U U						_			
👹 Eut 39.37 mil 💌 T1	Project tools:	in AIC tool holders, 5 in unde	fined location 5"/0.114mm} {In	sulate,Rubout	}		Depth [mil]:	Setup	2			
rubout tools: 0.125, 0.063,		Router bit 0.0394"	/1.001mm {Drill.C	ut}	-	2	c.s mii					
- 0.031, 0.010, 0.010, 0.000		R_39 Stub End Mill 0.010	0"/0.254mm {Ins	ulate Rubout I	Drill Cut Ster	til) a	30.0 mil					
¥ 0.110	THUS RODOU	FR7.5 Stub Epd Mill 0.015	6"/0 397mm /Inc	ulate Rubout I	Drill Cut Ster	cill.	3.0) mil 💌					
	URD4 Rubou	FR7.5 SEM_15	2"/0.705mm (Inc	ulato Bubout)		) (	(3.0) mil					
<u>201</u>	THUS Ru	Rubout tools					-					
	THOS Ru	Diameter [in]	Туре	Speed [rpm]	Plunge ral [in/m]	te Feed ra [in/m	ite Cor ]	mment				
Top Lawar	THUT RU	103 0.010 💌	Stub End Mill 🕑	(60000) 💌	default	7.5	*		_			
TERMOSENSE.TOP	🕞 🖁 Dri 🛽	0.016	Stub End Mill	(60000)	(40.0)	7.5	SEM_15		_			
TERMOSENSE.tap	🕞 🖁 Dri	05 0.0313 (1/32")	Stub End Mill	(60000)	(40.0)	(15.0)	CEM C2		_			
	🕞 🖁 Dri	0.125 (1/8")	Stub End Mill	(60000)	(40.0)	(15.0)	SEM 125					
	🕞 🖁 Dri	0.010	Stub End Mill	50000	35.0	7.5	501_125					
				1	-							
		Tool Table					ot t		Lat.			
	d	[in]	Type	Opera	tion	[rpm]	[in/m]	[in/m]	[mil]	Comment		
		TH03 0.010	Stub End Mill	All	5	ouuu	35.0 /	-5 -		M 15		
		THUE 0.016	Stub End Mill	Insulate &	Rubout d	efault	default d	efault -	50			
		1106 0.0625 (1/16")	Stub End Mill	All		efault	default d	efault -	SE	M_63	-	
		THU7 0.125 (1/8")	Stub End Mill	All	d	efault	default d	efault -	SE	M_125		
		TH02 undef	"V" 60°	Insulate &	Rubout d	efault	default d	lefault S	8 V_	_60		
		THO1 undef	"¥" 90°	Insulate &	Rubout d	efault	default d	lefault 4	5			
[Obj[1]: "TERMOSENSE.TOP"] total area [in2]: 4.233												
size [in]: 2.464 × 1.718 warnings: 4												
tool path: 64.19 in duration: ~5.02 min (F15.0 in/m)												
[Obj[2]: "TERMOSENSE.BOT"]										Select	2	
consistent press	warnings X7.93209 V6.07524 4v7 9324	9 dy-7.47476 d10.89909	2000dni [in]	Default	nnf	PhCNC Pr	o v4 2.5.7367 A 360	MTC	: 13.5e-6/*	C (ER4) @ 24.14°C	-	•
da ana ana ana ana ana ana ana ana ana a	activity for set	, aj, aroio5565	accession front	Derudita	p.,			miter	0)	-,,		

# 4.3.4 Drill tools

During the import of a new project "Drill Tools Table" contains the diameters of the tools that are actually in your project.

🐰 Dr	Drill Tool Table										
	hole [in]	Diameter [in]	Туре	Speed [rpm]	Plunge rate [in/m]	Feed rate [in/m]	Comment				
#1	0.031	0.031	Drill bit	(60000)	(40.0)	-	T1C0.031F2005100				
#2	0.039	0.039	Drill bit	(60000)	(40.0)	-	T2C0.039F2005100				
#3	0.059	0.059	Drill bit	(60000)	(40.0)	-	T3C0.059F2005100				
#4	0.110	0.110	Drill bit	(60000)	(40.0)	-	T4C0.110F2005100				
defaul	lt router: TO O	.0394"/1.000mm Ro	uter bit 56000	0 FR7.5 PR20.0	) R_39						

It is necessary to select the tools needed for the project. In a classic case (when the project comes from the same designer) most of the drilling tools are already in the tool holders (ATC models). The option <sup>\*</sup> select default
<sup>\*</sup> allow you to select a router bit to cut all holes that are larger than the bit diameter. This makes the hole diameter unlimited and saves on tools that you have to have at hand.



Shown below is the selection of 1mm (39.4 mil) router bit.

#### Start-up step-by-step

¥	V Drill Tool Table											
Г		hole [in]	Diameter [in]	Туре	Speed [rpm]	Plunge rate [in/m]	Feed rate [in/m]	Comment				
#	1	0.031	0.031	Drill bit	(60000)	(40.0)	-	T1C0.031F2005100				
#	2	0.039	0.039	Drill bit	(60000)	(40.0)	-	T2C0.039F2005100				
#	3	0.059	0.059	Drill bit	(60000)	(40.0)	-	T3C0.059F2005100				
#	4	0.110	0.110	Drill bit	(60000)	(40.0)	-	T4C0.110F2005100				
del												
	1/2	Apply defa	ult y Select	t default r tool	keset dr	ill table	Select A	TC Select				

Clicking on the button *k* automatically sets the holes that have to be routed.

	hole [in]	Diameter [in]	Туре	Speed [rpm]	Plunge rate	Feed rate	Comment
1	0.031	0.031	Drill bit	(60000)	(40.0)	-	T1C0.031F2005100
12	0.039	0.039	Drill bit	(60000)	(40.0)	-	T2C0.039F2005100
113	0.059	0.0394 (1.0mm)	Router	(60000)	(20.0)	(7.5)	R_39
113	0.110	0.0394 (1.0mm)	Router	(60000)	(20.0)	(7.5)	R_39
faul	router: TO C	1.0394"/1.000mm Ro	uter bit 56000	10 FR 7.5 PR 20.1	) R_39		

Shown bellow is an example of 31 mil drill bit selection from the main tool table.

FICINC			_	and the second second	the second second second								
File CAM CNC Setup Tool:	s Calc					ch							
=# 📲 🖬 👘 👘	♀ 212% ⊻	⊴ ♥ ₩ ₩	2 🔪 🖾 🔺	A → A	CNC Tools	(41)						Options, 🤤	<b></b> 1
2 NI 22 NI 13 NI													
- sea -+sea ( sea													
§ Insulate 8.00 mil ♀ 10													
§ Cut 39.37 mil ⊻ 11	<u> </u>												
vubout tools: 0.125, 0.063, 0.031, 0.016, 0.010, 0.008										×			
👷 drill tools: 0.031, 0.039, 0.059	a, .		hole	Diameter	Turne	Speed Pl	unge rate Fee	d rate	Comm	ant			
<sup>3</sup> 0.110			[in]	[in]	Type	[rpm]	[in/m] [ir	1/m] T1C0	.031E2009	5100			
	i ,		#1 0.031	0.031	Drill bit			T2C	0205200	5100			
		N T	w2 0.039	0.035	Drin bic (c	(4	0.0) -	120	.0391200	5100	x		
			Diameter	A Type	Operation	Speed	Plunge rate	Feed rate	Tool Tip	Comment			
			[in]	Stub End Mill	all	[rpm]	[in/m]	[in/m]	[mil]	Comment			
Top Layer			0.0197 (0.5mm)	Stub End M <sup>all</sup>		default	default	default		301_13			
TERMOSENSE.top		#5	0.025	Stub End Mill	All	default	default	default					
Bottom Layer		#4	0.023	Stub End Mill	01	default	default	default	-	CEM 63	_		
TERMOSENSE.BOT		THU	0.0825(1/18)	Stub End Mill	All	default	default	default		50-1_03	_		
		THO	0.123 (1/0 )	Scab Life Pilli	All Deill	default	default	uerauic	-	301-125			
		IHU	0.0135	Drill bit	Drill	default	default	-	-	DRL_13.5	_		
		IHU	0.022	Drill Dit	Drill	default	default		-	DRL_21.05			
			0.025	Drill bit	Drill	default	default	-	-	001-01	_		
			0.0015 (1/52 )	Drift Dit	Drill	default	default	-	-	DRL_31			
		1110	2 0.035	Drill Dic	Drill	derault	derault	-	-	DRL_39			
										Cr Se	lect		
			default router: TO	0.0394"/1.000mn	n Router bit 560000 FF	R7.5 PR20.0 R_	39		( n				
			vouter to	ol 🌽 r	outer tool	🖉 Reset drill t	able 🥻 S	select ATC	2	Select			
	-												
Obj[1]: "TERMOSENSE.TOP"] otal area [in2]: 4.233													
sze (inj: 2.464 x 1.718 warnings: 4													
:001 path: 64.19 in duration: ~5.02 min (F15.0 in/m)													
Ob[[2]: "TERMOSENSE.BOT"]													
otal area (in2): 4.233	4												
	(1) 4 warnings	X5.87930, Y5.6491	L3 dx5.87930, dy-7	.90088, d9.84835	2000dpi [in]	Default.mp	PhC	NC Pro v4.2.5.	7367.A360	MTCLE: 13.5e-6/*C	(FR4) @ 24.14°C		

Next screen shot shows completed Drill Tool Table.

🖁 Dri	ill Tool Table						
	hole [in]	Diameter [in]	Туре	Speed [rpm]	Plunge rate [in/m]	Feed rate [in/m]	Comment
TH 11	0.031	0.0313 (1/32")	Drill bit	(60000)	(40.0)	-	DRL_31
TH 12	0.039	0.035	Drill bit	(60000)	(40.0)	-	DRL_39
TH 13	0.059	0.0394 (1.0mm)	Router	(60000)	(20.0)	(7.5)	R_39
TH 13	0.110	0.0394 (1.0mm)	Router	(60000)	(20.0)	(7.5)	R_39
default router: T0 0.0394"/1.000mm Router bit 560000 FR7.5 PR20.0 R_39							
1	Apply defa router too	ult Select I Foute	t default r tool	🦆 Reset dr	ill table	Select A	TC Select

# 4.3.5 Project Tools

After all tools used in the project are entered, the Project Tools table will be as shown below.

Project Tools			×
Project tools: 11 in A	TC tool holders, 0 in undefined location	Depth [mil]:	U Insulate Tool
TH01 Insulate T0	"Y" 90° Tip(0.0045"/0.114mm)-{Insulate,Rubout}	(2.5) mil	~ becup
TH 13 Cut TO	Router bit 0.0394"/1.001mm {Drill,Cut} R_39	(80.0) mil	
TH03 Rubout T1	Stub End Mill 0.0100"/0.254mm {Insulate,Rubout,Drill,Cut,Stencil}	(3.0) mil	
TH04 Rubout T2	Stub End Mill 0.0156"/0.397mm {Insulate,Rubout,Drill,Cut,Stencil} SEM_15	(3.0) mil	
THOS Rubout T3	Stub End Mill 0.0313"/0.795mm {Insulate,Rubout}	(3.0) mil	
THUE Rubout T4	Stub End Mill 0.0625"/1.587mm {Insulate,Rubout,Drill,Eut,Stencil} SEM 63	(3.0) mil	
THN7 Rubout T5	Stub End Mill 0.1250"/3.175mm {Insulate,Rubout,Drill,Cut,Stencil} SEM_125	(3.0) mil	
TH 11 Drill T1	Drill bit 0.0313"/0.795mm {Drill} DRL_31	(80.0) mil	
TH 12 Drill T2	Drill bit 0.0350"/0.889mm {Drill} DRL_39	(80.0) mil	
TH 13 Drill T3	Router bit 0.0394"/1.000mm {Drill,Cut} R 39	(80.0) mil	
TH 13 Drill T4		(80.0) mil	
	-		
			Auto tool depth     update

You can edit the tool penetration in the Project Tools table. Our recommendation is to use default values (shown in brackets) and if needed, on repeated basis, change the default values in order to save time during the setup.

Have in mind that penetration tool settings smaller than 3 mil do not work fine on all materials.

Basically this depend of the hardness of the substrate and the type of tool in use. For example, relatively soft (Teflon based) substrates, combined with non center cutting tools (all V tools), will yield down and will not remove the copper in some spots during the process of insulation.

Typical values of the tool penetration using 1/16 thick FR4 material are:

- insulation, 3-4 mil if end mill is used or calculated depth if V tool is used
- copper rubout, 3-4 mil
- drilling and routing 80 mil.

# 5. Project positioning on the work piece and machining

# **5.1 Project positioning**

After all needed files are imported and the material is mounted on the machine table we need to position the project on the material.

The positioning of the project can be done many ways but the easiest and most accurate is to use fiducial registration with the machine camera.

• place the center of the photo-tool (supplied with the system) on the upper left corner of the material. Recommended is to have 1/2 inch (12-13 mm) distance from the material edges. This will allow the pressure foot to be always on the material surface. It has 1 inch (25.4 mm diameter.

- turn the camera on and focus it on the photo tool
- find the photo tool center
- using the mouse find (zoom in as needed) the upper left corner of the project and make a right click.
- select "Move to Camera Position (Fiducial Point 1)" from the popup menu.



The upper left corner of your project now will move to the desired point. In the center of the photo-tool.



The project is now ready for machining.

In the video clip below are shown the operations related to the import of the project, project tools handling and project positioning.

Import Gerbers, Tool settings & Project aligment (video): <u>http://youtu.be/yTY14RlfLRc</u>

# 5.2 Project execution (machining)

After all tools are arranged and the project is positioned on the material, we can start machining it. The process will be started after you click on RUN (GO), it will execute currently selected process.

We will recommend you to use processing that links all programs related to the side under machining. For example "Entire Top". In a typical case it will run 3 process "Insulation top",

"Rubout top" (if selected rubout region(s) exist) and "Drill top". After finish all it will wait for the operator to flip the board. After flipping the board and performing the fiducial registration for the bottom side you can select "Entire bottom". It is recommended to use center of the table to have the project registration holes for camera access.

In the video clip below you can se the process of fiducial registration between top and bottom sides of the board. This system of the registration between the board (layers) is many times more accurate than any mechanical registration.

Fiducial registration (video): <u>http://www.youtube.com/watch?v=aGGKzJjflwU</u>

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